



Product name:
Industrial Robot Loading and Unloading Training System

Product code:
CIVIL-UTS-84-0001



Description

Industrial Robot Loading and Unloading Training System

Technical specification

3. Industrial robot electrical part cognition
4. Industrial Robot Controller Cognition
5. Learning and training of Six axis Robot Joint Motion Control
6. Learning and training of Linear Motion Trajectory Control of Six-axis industrial robot
7. Learning and training of circular motion trajectory of Six-axis industrial robot
8. Learning and Training Acceleration / Deceleration Constraint Control of Six-axis industrial robot
9. Robot control basic operation training
10. Robot coordinate system (tool coordinates, user coordinates) application operation training
11. Robot operation and teaching programming training
12. Robot Typical Application - Application of Machine Tool Loading and Unloading
13. Machine tool principle, structure learning
14. Classification and Function of CNC Machine Tool
15. Learning of numerical control system
16. Application Technology of CNC Machine Tool
17. CNC machine tool operation and programming

Overview

The industrial robot loading and unloading training system will grab the workpiece being processed and place it on the machine. After processing, the robot will take the workpieces to the visual system for inspection. Here the workpieces are qualified for transfer to the following steps.

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Model number: DLRB-1410B (other brands available)

Email us at: export@civilmechanicalindia.com

Wrist overweight: 5 kg

Axes: 6-axis

Max wingspan radius: 1.44m

Protection grade: IP54

Installation Way: ground installation

Positional repeatability: 0.05 mm

Power supply: three-phase 400V(+10%,-15%),50Hz/60Hz

Rated power: 4.5KVA

Training content

1. Basic Principles and Constitution of Industrial Robots
2. Cognition of Industrial Robot Ontology